

Engineering Formula Sheet

Statistics

Mean

$$\mu = \frac{\sum x_i}{n}$$

μ = mean value
 $\sum x_i$ = sum of all data values (x_1, x_2, x_3, \dots)
 n = number of data values

Standard Deviation

$$\sigma = \sqrt{\frac{\sum (x_i - \mu)^2}{n}}$$

σ = standard deviation
 x_i = individual data value (x_1, x_2, x_3, \dots)
 μ = mean value
 n = number of data values

Mode

Place data in ascending order.
 Mode = most frequently occurring value

If two values occur at the maximum frequency the data set is *bimodal*.

If three or more values occur at the maximum frequency the data set is *multi-modal*.

Median

Place data in ascending order.
 If n is odd, median = central value
 If n is even, median = mean of two central values

n = number of data values

Range

Range = $x_{\max} - x_{\min}$

x_{\max} = maximum data value
 x_{\min} = minimum data value

Probability

Frequency

$$f_x = \frac{n_x}{n}$$

$$P_x = \frac{f_x}{f_a}$$

f_x = relative frequency of outcome x
 n_x = number of events with outcome x
 n = total number of events
 P_x = probability of outcome x
 f_a = frequency of all events

Binomial Probability (order doesn't matter)

$$P_k = \frac{n!(p^k)(q^{n-k})}{k!(n-k)!}$$

P_k = binomial probability of k successes in n trials
 p = probability of a success
 $q = 1 - p$ = probability of failure
 k = number of successes
 n = number of trials

Independent Events

$$P(A \text{ and } B \text{ and } C) = P_A P_B P_C$$

$P(A \text{ and } B \text{ and } C)$ = probability of independent events A and B and C occurring in sequence

P_A = probability of event A

Mutually Exclusive Events

$$P(A \text{ or } B) = P_A + P_B$$

$P(A \text{ or } B)$ = probability of either mutually exclusive event A or B occurring in a trial

P_A = probability of event A

$\sum x_i$ = sum of all data values (x_1, x_2, x_3, \dots)
 n = number of data values

Conditional Probability

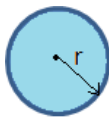
$$P(A|D) = \frac{P(A) \cdot P(D|A)}{P(A) \cdot P(D|A) + P(\sim A) \cdot P(D|\sim A)}$$

$P(A|D)$ = probability of event A given event D
 $P(A)$ = probability of event A occurring
 $P(\sim A)$ = probability of event A not occurring
 $P(D|\sim A)$ = probability of event D given event A did not occur

Plane Geometry

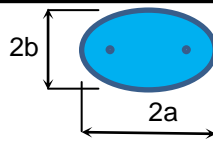
Circle

Circumference = $2 \pi r$
Area = πr^2



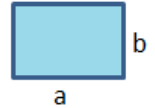
Ellipse

Area = $\pi a b$



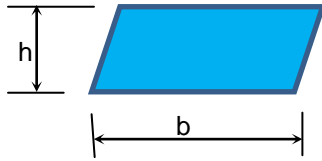
Rectangle

Perimeter = $2a + 2b$
Area = ab



Parallelogram

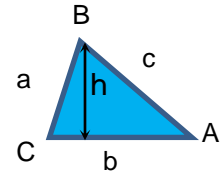
Area = bh



Triangle

Area = $\frac{1}{2} bh$

$a^2 = b^2 + c^2 - 2bc \cdot \cos \angle A$
 $b^2 = a^2 + c^2 - 2ac \cdot \cos \angle B$
 $c^2 = a^2 + b^2 - 2ab \cdot \cos \angle C$



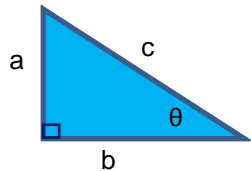
Right Triangle

$c^2 = a^2 + b^2$

$\sin \theta = \frac{a}{c}$

$\cos \theta = \frac{b}{c}$

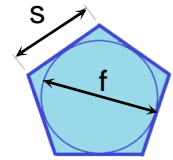
$\tan \theta = \frac{a}{b}$



Regular Polygons

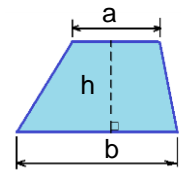
Area = $n \frac{s(\frac{1}{2} f)}{2}$

n = number of sides



Trapezoid

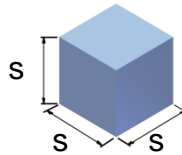
Area = $\frac{1}{2}(a + b)h$



Solid Geometry

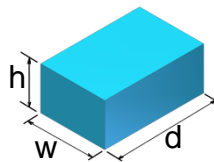
Cube

Volume = s^3
Surface Area = $6s^2$



Rectangular Prism

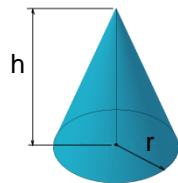
Volume = $w d h$
Surface Area = $2(wd + wh + dh)$



Right Circular Cone

Volume = $\frac{\pi r^2 h}{3}$

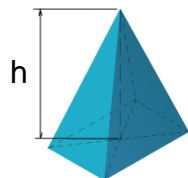
Surface Area = $\pi r \sqrt{r^2 + h^2}$



Pyramid

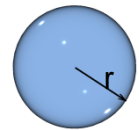
Volume = $\frac{A h}{3}$

A = area of base



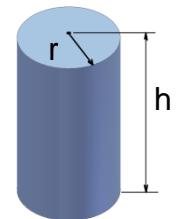
Sphere

Volume $\frac{4}{3} \pi r^3$
Surface Area = $4 \pi r^2$



Cylinder

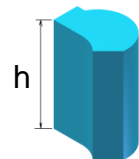
Volume = $\pi r^2 h$
Surface Area = $2 \pi r h + 2 \pi r^2$



Irregular Prism

Volume = $A h$

A = area of base



Constants

$g = 9.8 \text{ m/s}^2 = 32.27 \text{ ft/s}^2$

$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg} \cdot \text{s}^2$

$\pi = 3.14159$

Conversions

Mass

$$\begin{aligned} 1 \text{ kg} &= 2.205 \text{ lb}_m \\ 1 \text{ slug} &= 32.2 \text{ lb}_m \\ 1 \text{ ton} &= 2000 \text{ lb}_m \end{aligned}$$

Area

$$\begin{aligned} 1 \text{ acre} &= 4047 \text{ m}^2 \\ &= 43,560 \text{ ft}^2 \\ &= 0.00156 \text{ mi}^2 \end{aligned}$$

Force

$$\begin{aligned} 1 \text{ N} &= 0.225 \text{ lb}_f \\ 1 \text{ kip} &= 1,000 \text{ lb}_f \end{aligned}$$

Energy

$$\begin{aligned} 1 \text{ J} &= 0.239 \text{ cal} \\ &= 9.48 \times 10^{-4} \text{ Btu} \\ &= 0.7376 \text{ ft}\cdot\text{lb}_f \\ 1 \text{ kW h} &= 3,600,000 \text{ J} \end{aligned}$$

Length

$$\begin{aligned} 1 \text{ m} &= 3.28 \text{ ft} \\ 1 \text{ km} &= 0.621 \text{ mi} \\ 1 \text{ in.} &= 2.54 \text{ cm} \\ 1 \text{ mi} &= 5280 \text{ ft} \\ 1 \text{ yd} &= 3 \text{ ft} \end{aligned}$$

Volume

$$\begin{aligned} 1 \text{ L} &= 0.264 \text{ gal} \\ &= 0.0353 \text{ ft}^3 \\ &= 33.8 \text{ fl oz} \\ 1 \text{ mL} &= 1 \text{ cm}^3 = 1 \text{ cc} \end{aligned}$$

Pressure

$$\begin{aligned} 1 \text{ atm} &= 1.01325 \text{ bar} \\ &= 33.9 \text{ ft H}_2\text{O} \\ &= 29.92 \text{ in. Hg} \\ &= 760 \text{ mm Hg} \\ &= 101,325 \text{ Pa} \\ &= 14.7 \text{ psi} \\ 1 \text{ psi} &= 2.31 \text{ ft of H}_2\text{O} \end{aligned}$$

Defined Units

$$\begin{aligned} 1 \text{ J} &= 1 \text{ N}\cdot\text{m} \\ 1 \text{ N} &= 1 \text{ kg}\cdot\text{m} / \text{s}^2 \\ 1 \text{ Pa} &= 1 \text{ N} / \text{m}^2 \\ 1 \text{ V} &= 1 \text{ W} / \text{A} \\ 1 \text{ W} &= 1 \text{ J} / \text{s} \\ 1 \text{ W} &= 1 \text{ V} / \text{A} \\ 1 \text{ Hz} &= 1 \text{ s}^{-1} \\ 1 \text{ F} &= 1 \text{ A}\cdot\text{s} / \text{V} \\ 1 \text{ H} &= 1 \text{ V}\cdot\text{s} / \text{A} \end{aligned}$$

Temperature Change

$$\begin{aligned} 1 \text{ K} &= 1 \text{ }^\circ\text{C} \\ &= 1.8 \text{ }^\circ\text{F} \\ &= 1.8 \text{ }^\circ\text{R} \end{aligned}$$

Time

$$\begin{aligned} 1 \text{ d} &= 24 \text{ h} \\ 1 \text{ h} &= 60 \text{ min} \\ 1 \text{ min} &= 60 \text{ s} \\ 1 \text{ yr} &= 365 \text{ d} \end{aligned}$$

Power

$$\begin{aligned} 1 \text{ W} &= 3.412 \text{ Btu/h} \\ &= 0.00134 \text{ hp} \\ &= 14.34 \text{ cal/min} \\ &= 0.7376 \text{ ft}\cdot\text{lb}_f/\text{s} \end{aligned}$$

SI Prefixes

Numbers Less Than One

Power of 10	Prefix	Abbreviation
10^{-1}	deci-	d
10^{-2}	centi-	c
10^{-3}	milli-	m
10^{-6}	micro-	μ
10^{-9}	nano-	n
10^{-12}	pico-	p
10^{-15}	femto-	f
10^{-18}	atto-	a
10^{-21}	zepto-	z
10^{-24}	yocto-	y

Numbers Greater Than One

Power of 10	Prefix	Abbreviation
10^1	deca-	da
10^2	hecto-	h
10^3	kilo-	k
10^6	Mega-	M
10^9	Giga-	G
10^{12}	Tera-	T
10^{15}	Peta-	P
10^{18}	Exa-	E
10^{21}	Zetta-	Z
10^{24}	Yotta-	Y

Equations

Mass and Weight

$$M = VD_m$$

$$W = mg$$

$$W = VD_w$$

V = volume

D_m = mass density

m = mass

D_w = weight density

g = acceleration due to gravity

Temperature

$$T_K = T_C + 273$$

$$T_R = T_F + 460$$

$$\frac{T_F - 32}{180} = \frac{T_C}{100}$$

T_K = temperature in Kelvin

T_C = temperature in Celsius

T_R = temperature in Rankin

T_F = temperature in Fahrenheit

Force

$$F = ma$$

F = force

m = mass

a = acceleration

Equations of Static Equilibrium

$$\sum F_x = 0 \quad \sum F_y = 0 \quad \sum M_P = 0$$

F_x = force in the x-direction

F_y = force in the y-direction

M_P = moment about point P

Equations (Continued)

Energy: Work

$$W = F \cdot d$$

W = work
F = force
d = distance

Power

$$P = \frac{E}{t} = \frac{W}{t}$$

$$P = \frac{\tau \cdot \text{rpm}}{5252}$$

P = power
E = energy
W = work
t = time
 τ = torque
rpm = revolutions per minute

Efficiency

$$\text{Efficiency (\%)} = \frac{P_{\text{out}}}{P_{\text{in}}} \cdot 100\%$$

P_{out} = useful power output
 P_{in} = total power input

Energy: Potential

$$U = mgh$$

U = potential energy
m = mass
g = acceleration due to gravity
h = height

Energy: Kinetic

$$K = \frac{1}{2} mv^2$$

K = kinetic energy
m = mass
v = velocity

Energy: Thermal

$$Q = mc\Delta T$$

Q = thermal energy
m = mass
c = specific heat
 ΔT = change in temperature

Fluid Mechanics

$$P = \frac{F}{A}$$

$$\frac{V_1}{T_1} = \frac{V_2}{T_2} \quad (\text{Charles' Law})$$

$$\frac{P_1}{T_1} = \frac{P_2}{T_2} \quad (\text{Gay-Lussanc's Law})$$

$$P_1V_1 = P_2V_2 \quad (\text{Boyle's Law})$$

$$Q = Av$$

$$A_1v_1 = A_2v_2$$

$$\text{Horsepower} = \frac{QP}{1714}$$

absolute pressure = gauge pressure
+ atmospheric pressure

P = absolute pressure
F = Force
A = Area
V = volume
T = absolute temperature
Q = flow rate
v = flow velocity

Mechanics

$$s = \frac{d}{t} \quad (\text{where acceleration} = 0)$$

$$v = \frac{d}{t} \quad (\text{where acceleration} = 0)$$

$$a = \frac{v_f - v_i}{t}$$

$$X = \frac{v_i \sin(2\theta)}{-g}$$

$$v = v_0 + at$$

$$d = d_0 + v_0t + \frac{1}{2}at^2$$

$$v^2 = v_0^2 + 2a(d - d_0)$$

$$\tau = dF \sin \theta$$

s = speed
v = velocity
a = acceleration
X = range
t = time
d = distance
g = acceleration due to gravity
d = distance
 θ = angle
 τ = torque
F = force

Electricity

Ohm's Law

$$V = IR$$

$$P = IV$$

$$R_T \text{ (series)} = R_1 + R_2 + \dots + R_n$$

$$R_T \text{ (parallel)} = \frac{1}{\frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_n}}$$

Kirchhoff's Current Law

$$I_T = I_1 + I_2 + \dots + I_n$$

$$\text{or } I_T = \sum_{k=1}^n I_k$$

Kirchhoff's Voltage Law

$$V_T = V_1 + V_2 + \dots + V_n$$

$$\text{or } V_T = \sum_{k=1}^n V_k$$

V = voltage

V_T = total voltage

I = current

I_T = total current

R = resistance

R_T = total resistance

P = power

Thermodynamics

$$P = Q' = AU\Delta T$$

$$P = \frac{Q}{\Delta t}$$

$$U = \frac{1}{R} = \frac{k}{L}$$

$$P = \frac{kA\Delta T}{L}$$

$$A_1v_1 = A_2v_2$$

$$P_{\text{net}} = \sigma Ae(T_2^4 - T_1^4)$$

P = rate of heat transfer

Q = thermal energy

A = Area of thermal conductivity

U = coefficient of heat conductivity
(U-factor)

ΔT = change in temperature

Δt = change in time

R = resistance to heat flow (R-value)

k = thermal conductivity

v = velocity

P_{net} = net power radiated

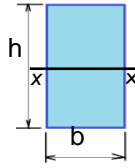
$$\sigma = 5.6696 \times 10^{-8} \frac{\text{W}}{\text{m}^2 \cdot \text{K}^4}$$

e = emissivity constant

Section Properties

Moment of Inertia

$$I_{xx} = \frac{bh^3}{12}$$



I_{xx} = moment of inertia of a rectangular section about x-x axis

Complex Shapes Centroid

$$\bar{x} = \frac{\sum x_i A_i}{\sum A_i} \quad \text{and} \quad \bar{y} = \frac{\sum y_i A_i}{\sum A_i}$$

\bar{x} = x-distance to the centroid

\bar{y} = y-distance to the centroid

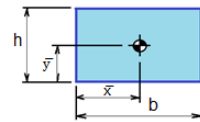
x_i = x distance to centroid of shape i

y_i = y distance to centroid of shape i

A_i = Area of shape i

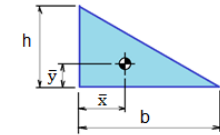
Rectangle Centroid

$$\bar{x} = \frac{b}{2} \quad \text{and} \quad \bar{y} = \frac{h}{2}$$



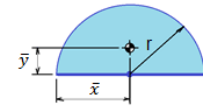
Right Triangle Centroid

$$\bar{x} = \frac{b}{3} \quad \text{and} \quad \bar{y} = \frac{h}{3}$$



Semi-circle Centroid

$$\bar{x} = r \quad \text{and} \quad \bar{y} = \frac{4r}{3\pi}$$



\bar{x} = x-distance to the centroid

\bar{y} = y-distance to the centroid

Material Properties

Stress (axial)

$$\sigma = \frac{F}{A}$$

σ = stress

F = axial force

A = cross-sectional area

Strain (axial)

$$\epsilon = \frac{\delta}{L_0}$$

ϵ = strain

L_0 = original length

δ = change in length

Modulus of Elasticity

$$E = \frac{\sigma}{\epsilon}$$

$$E = \frac{\sigma(F_2 - F_1)L_0}{(\delta_2 - \delta_1)A}$$

E = modulus of elasticity

σ = stress

ϵ = strain

A = cross-sectional area

F = axial force

δ = deformation

Structural Analysis

Beam Formulas

	<p>Reaction $R_A = R_B = \frac{P}{2}$</p> <p>Moment $M_{\max} = \frac{PL}{4}$ (at point of load)</p> <p>Deflection $\Delta_{\max} = \frac{PL^3}{48EI}$ (at point of load)</p>
	<p>Reaction $R_A = R_B = \frac{\omega L}{2}$</p> <p>Moment $M_{\max} = \frac{\omega L^2}{8}$ (at center)</p> <p>Deflection $\Delta_{\max} = \frac{5\omega L^4}{384EI}$ (at center)</p>
	<p>Reaction $R_A = R_B = P$</p> <p>Moment $M_{\max} = Pa$ (between loads)</p> <p>Deflection $\Delta_{\max} = \frac{Pa}{24EI}(3L^2 - 4a^2)$ (at center)</p>
	<p>Reaction $R_A = \frac{Pb}{L}$ and $R_B = \frac{Pa}{L}$</p> <p>Moment $M_{\max} = \frac{Pab}{L}$ (at Point of Load)</p> <p>Deflection $\Delta_{\max} = \frac{Pab(a+2b)\sqrt{3a(a+2b)}}{27EI}$ (at $x = \sqrt{\frac{a(a+2b)}{3}}$ when $a > b$)</p>

Deformation: Axial

$$\delta = \frac{FL_0}{AE}$$

δ = deformation

F = axial force

L_0 = original length

A = cross-sectional area

E = modulus of elasticity

Truss Analysis

$$2J = M + R$$

J = number of joints

M = number of members

R = number of reaction forces

Simple Machines

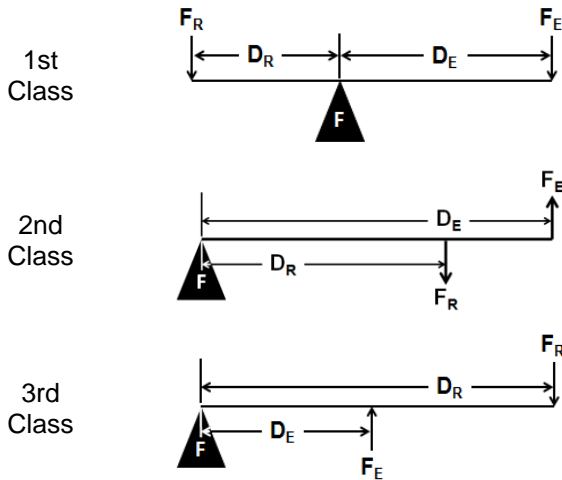
Mechanical Advantage (MA)

$$IMA = \frac{D_E}{D_R} \qquad AMA = \frac{F_R}{F_E}$$

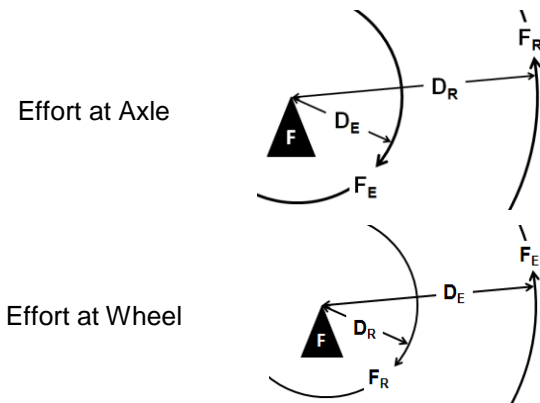
$$\% \text{ Efficiency} = \left(\frac{AMA}{IMA} \right) 100$$

IMA = Ideal Mechanical Advantage
 AMA = Actual Mechanical Advantage
 D_E = Effort Distance D_R = Resistance Distance
 F_E = Effort Force F_R = Resistance Force

Lever



Wheel and Axle



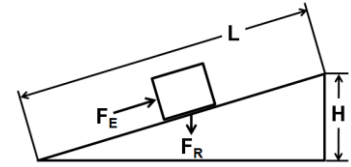
Pulley Systems

IMA = Total number of strands of a single string supporting the resistance

$$IMA = \frac{D_E \text{ (string pulled)}}{D_R \text{ (resistance lifted)}}$$

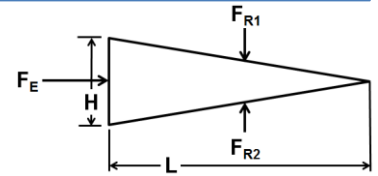
Inclined Plane

$$IMA = \frac{L \text{ (slope)}}{H}$$



Wedge

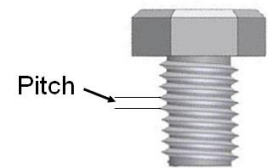
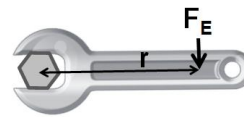
$$IMA = \frac{L \text{ (L to height)}}{H}$$



Screw

$$IMA = \frac{C}{\text{Pitch}}$$

$$\text{Pitch} = \frac{1}{\text{TPI}}$$



C = Circumference
 r = radius
 Pitch = distance between threads
 TPI = Threads Per Inch

Compound Machines

$$MA_{\text{TOTAL}} = (MA_1) (MA_2) (MA_3) \dots$$

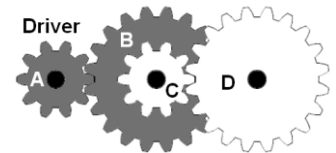
Gears; Sprockets with Chains; and Pulleys with Belts Ratios

$$GR = \frac{N_{\text{out}}}{N_{\text{in}}} = \frac{d_{\text{out}}}{d_{\text{in}}} = \frac{\omega_{\text{in}}}{\omega_{\text{out}}} = \frac{T_{\text{out}}}{T_{\text{in}}}$$

$$\frac{d_{\text{out}}}{d_{\text{in}}} = \frac{\omega_{\text{in}}}{\omega_{\text{out}}} = \frac{T_{\text{out}}}{T_{\text{in}}} \text{ (pulleys)}$$

Compound Gears

$$GR_{\text{TOTAL}} = \left(\frac{B}{A} \right) \left(\frac{D}{C} \right)$$



GR = Gear Ratio

ω_{in} = Angular Velocity - driver

ω_{out} = Angular Velocity - driven

N_{in} = Number of Teeth - driver

N_{out} = Number of Teeth - driven

d_{in} = Diameter - driver

d_{out} = Diameter - driven

T_{in} = Torque - driver

T_{out} = Torque - driven

Structural Design

Steel Beam Design: Shear

$$V_a = \frac{V_n}{\Omega_v}$$

$$V_n = 0.6F_y A_w$$

V_a = allowable shear strength
 V_n = nominal shear strength
 $\Omega_v = 1.5$ = factor of safety for shear
 F_y = yield stress
 A_w = area of web

Steel Beam Design: Moment

$$M_a = \frac{M_n}{\Omega_b}$$

$$M_n = F_y Z_x$$

M_a = allowable bending moment
 M_n = nominal moment strength
 $\Omega_b = 1.67$ = factor of safety for bending moment
 F_y = yield stress
 Z_x = plastic section modulus about neutral axis

Spread Footing Design

$$Q_{net} = Q_{allowable} - P_{footing}$$

$$P_{footing} = t_{footing} \cdot 150 \frac{lb}{ft^2}$$

$$q = \frac{P}{A}$$

Q_{net} = net allowable soil bearing pressure
 $Q_{allowable}$ = total allowable soil bearing pressure
 $P_{footing}$ = soil bearing pressure due to footing weight
 $t_{footing}$ = thickness of footing
 q = soil bearing pressure
 P = column load applied
 A = area of footing

Storm Water Runoff

Storm Water Drainage

$$Q = C_f C_i A$$

$$C_c = \frac{C_1 A_1 + C_2 A_2 + \dots}{A_1 + A_2 + \dots}$$

Q = peak storm water runoff rate (ft³/s)
 C_f = runoff coefficient adjustment factor
 C = runoff coefficient
 i = rainfall intensity (in./h)
 A = drainage area (acres)

Runoff Coefficient Adjustment Factor

Return Period	C_f
1, 2, 5, 10	1.0
25	1.1
50	1.2
100	1.25

Rational Method Runoff Coefficients

Categorized by Surface

Forested	0.059—0.2
Asphalt	0.7—0.95
Brick	0.7—0.85
Concrete	0.8—0.95
Shingle roof	0.75—0.95
Lawns, well drained (sandy soil)	
Up to 2% slope	0.05—0.1
2% to 7% slope	0.10—0.15
Over 7% slope	0.15—0.2
Lawns, poor drainage (clay soil)	
Up to 2% slope	0.13—0.17
2% to 7% slope	0.18—0.22
Over 7% slope	0.25—0.35
Driveways,	0.75—0.85

Categorized by Use

Farmland	0.05—0.3
Pasture	0.05—0.3
Unimproved	0.1—0.3
Parks	0.1—0.25
Cemeteries	0.1—0.25
Railroad yard	0.2—0.40
Playgrounds	0.2—0.35

Business Districts

Neighborhood	0.5—0.7
City (downtown)	0.7—0.95
Residential	
Single-family	0.3—0.5
Multi-plexes,	0.4—0.6
Multi-plexes,	0.6—0.75
Suburban	0.25—0.4
Apartments,	0.5—0.7

Industrial

Light	0.5—0.8
Heavy	0.6—0.9

Water Supply

Hazen-Williams Formula

$$h_f = \frac{10.44LQ^{1.85}}{C^{1.85}d^{4.8655}}$$

h_f = head loss due to friction (ft of H₂O)
 L = length of pipe (ft)
 Q = water flow rate (gpm)
 C = Hazen-Williams constant
 d = diameter of pipe (in.)

Dynamic Head

dynamic head = static head – head loss

Hazen-Williams Constants

Pipe Material	Typical Range	Clean, New Pipe	Typical Design Value
Cast Iron and Wrought Iron	80 - 150	130	100
Copper, Glass or Brass	120 - 150	140	130
Cement lined Steel or Iron	120 - 150	150	140
Plastic PVC or ABS	120 - 150	140	130
Steel, welded and seamless or interior riveted	80-150	140	100

Equivalent Length of (Generic) Fittings

	Pipe Size													
	1/4	3/8	1/2	3/4	1	1 1/4	1 1/2	2	2 1/2	3	4	5	6	
Screwed Fittings														
Elbows	2.3	3.1	3.6	4.4	5.2	6.6	7.4	8.5	9.3	11.0	13.0	15.0	17.0	21.0
Long radius 90 degree	1.5	2.0	2.2	2.3	2.7	3.2	3.4	3.6	3.6	4.0	4.6	5.0	5.7	7.0
Regular 45 degree	0.3	0.5	0.7	0.9	1.3	1.7	2.1	2.7	3.2	4.0	5.5	7.0	9.3	13.0
Line Flow	0.8	1.2	1.7	2.4	3.2	4.6	5.6	7.7	9.3	12.0	17.0	22.0	27.0	38.0
Branch Flow	2.4	3.5	4.2	5.3	6.6	8.7	9.9	12.0	13.0	17.0	21.0	27.0	34.0	42.0
Return Bends	2.3	3.1	3.6	4.4	5.2	6.6	7.4	8.5	9.3	11.0	13.0	15.0	17.0	21.0
Regular 180 degree	21.0	22.0	22.0	24.0	29.0	37.0	42.0	54.0	62.0	79.0	110.0	140.0	180.0	240.0
Globe														
Gate	0.3	0.5	0.6	0.7	0.8	1.1	1.2	1.5	1.7	1.9	2.5	3.0	3.8	5.0
Angle	12.8	15.0	15.0	15.0	17.0	18.0	18.0	18.0	18.0	18.0	18.0	18.0	18.0	18.0
Swing Check	7.2	7.3	8.0	8.8	11.0	13.0	15.0	19.0	22.0	27.0	38.0	50.0	65.0	85.0
Strainer		4.6	5.0	6.6	7.7	18.0	20.0	27.0	29.0	34.0	42.0	50.0	65.0	85.0

	Pipe Size																	
	1/2	3/4	1	1 1/4	1 1/2	2	2 1/2	3	4	5	6	8	10	12	14	16	18	
Flanged Fittings																		
Elbows	0.9	1.2	1.6	2.1	2.4	3.1	3.6	4.4	5.9	7.3	8.9	12.0	14.0	17.0	18.0	21.0	23.0	
Long radius 90 degree	1.1	1.3	1.6	2.0	2.3	2.7	2.7	3.4	4.2	5.0	5.7	7.0	8.0	9.0	9.4	10.0	11.0	
Regular 45 degree	0.5	0.6	0.8	1.1	1.3	1.7	2.0	2.6	3.5	4.5	5.6	7.7	9.0	11.0	13.0	15.0	18.0	
Line Flow	0.7	0.8	1.0	1.3	1.5	1.8	1.9	2.2	2.8	3.3	3.8	4.7	5.2	6.0	6.4	7.2	7.6	
Branch Flow	2.0	2.6	3.3	4.4	5.2	6.6	7.5	9.4	12.0	15.0	18.0	24.0	30.0	34.0	37.0	43.0	47.0	
Return Bends	0.9	1.2	1.6	2.1	2.4	3.1	3.6	4.4	5.9	7.3	8.9	12.0	14.0	17.0	18.0	21.0	23.0	
Regular 180 degree	1.1	1.3	1.6	2.0	2.3	2.7	2.9	3.4	4.2	5.0	5.7	7.0	8.0	9.0	9.4	10.0	11.0	
Long radius 180 degree																		
Globe	38.0	40.0	45.0	54.0	59.0	70.0	77.0	94.0	120.0	150.0	190.0	260.0	310.0	390.0				
Gate						2.6	2.7	2.8	2.9	3.1	3.2	3.2	3.2	3.2	3.2	3.2	3.2	3.2
Angle	15.0	15.0	17.0	18.0	18.0	21.0	22.0	28.0	38.0	50.0	65.0	90.0	120.0	140.0	160.0	190.0	210.0	210.0
Swing Check	3.8	5.3	7.2	10.0	12.0	17.0	21.0	27.0	38.0	50.0	65.0	90.0	120.0	140.0	160.0	190.0	210.0	210.0

555 Timer Design Equations

$$T = 0.693 (R_A + 2R_B)C$$

$$f = \frac{1}{T}$$

$$\text{duty-cycle} = \frac{(R_A + R_B)}{(R_A + 2R_B)} \cdot 100\%$$

T = period

f = frequency

R_A = resistance A

R_B = resistance B

C = capacitance

Boolean Algebra

Boolean Theorems

$$X \cdot 0 = 0$$

$$X \cdot 1 = X$$

$$X \cdot X = X$$

$$X \cdot \bar{X} = 0$$

$$X + 0 = X$$

$$X + 1 = 1$$

$$X + X = X$$

$$X + \bar{X} = 1$$

$$\bar{\bar{X}} = X$$

Commutative Law

$$X \cdot Y = Y \cdot X$$

$$X + Y = Y + X$$

Associative Law

$$X(YZ) = (XY)Z$$

$$X + (Y + Z) = (X + Y) + Z$$

Distributive Law

$$X(Y+Z) = XY + XZ$$

$$(X+Y)(W+Z) = XW+XZ+YW+YZ$$

Consensus Theorems

$$X + \bar{X}Y = X + Y$$

$$X + \bar{X}\bar{Y} = X + \bar{Y}$$

$$\bar{X} + XY = \bar{X} + Y$$

$$\bar{X} + X\bar{Y} = \bar{X} + \bar{Y}$$

DeMorgan's Theorems

$$\overline{XY} = \bar{X} + \bar{Y}$$

$$\overline{X+Y} = \bar{X} \cdot \bar{Y}$$

Speeds and Feeds

$$N = \frac{CS \left(12 \frac{\text{in.}}{\text{ft}}\right)}{\pi d}$$

$$f_m = f_t \cdot n_t \cdot N$$

$$\text{Plunge Rate} = \frac{1}{2} \cdot f_m$$

N = spindle speed (rpm)

CS = cutting speed (in./min)

d = diameter (in.)

f_m = feed rate (in./min)

f_t = feed (in./tooth)

n_t = number of teeth

Aerospace Equations

Forces of Flight

$$C_D = \frac{2D}{\rho v^2 A}$$

$$R_e = \frac{\rho v l}{\mu}$$

$$C_L = \frac{2L}{\rho v^2 A}$$

$$M = Fd$$

C_L = coefficient of lift
 C_D = coefficient of drag
 L = lift
 D = drag
 A = wing area
 ρ = density
 R_e = Reynolds number
 v = velocity
 l = length of fluid travel
 μ = fluid viscosity
 F = force
 m = mass
 g = acceleration due to gravity
 M = moment
 d = moment arm (distance from datum perpendicular to F)

Propulsion

$$F_N = W(v_j - v_o)$$

$$I = F_{ave} \Delta t$$

$$F_{net} = F_{avg} - F_g$$

$$a = v_f \Delta t$$

F_N = net thrust
 W = air mass flow
 v_o = flight velocity
 v_j = jet velocity
 I = total impulse
 F_{ave} = average thrust force
 Δt = change in time (thrust duration)
 F_{net} = net force
 F_{avg} = average force
 F_g = force of gravity
 v_f = final velocity
 a = acceleration
 Δt = change in time (thrust duration)

NOTE: F_{ave} and F_{avg} are easily confused.

Energy

$$K = \frac{1}{2} m v^2$$

$$U = \frac{-GMm}{R}$$

$$E = U + K = -\frac{GMm}{2R}$$

K = kinetic energy
 m = mass
 v = velocity
 U = gravitational potential energy
 G = universal gravitation constant
 M = mass of central body
 m = mass of orbiting object
 R = Distance center main body to center of orbiting object
 E = Total Energy of an orbit

Orbital Mechanics

$$e = \sqrt{1 - \frac{b^2}{a^2}}$$

$$T = 2\pi \frac{a^3}{\sqrt{\mu}} = 2\pi \frac{a^3}{\sqrt{GM}}$$

$$F = \frac{GMm}{r^2}$$

e = eccentricity
 b = semi-minor axis
 a = semi-major axis
 T = orbital period
 a = semi-major axis
 μ = gravitational parameter
 F = force of gravity between two bodies
 G = universal gravitation constant
 M = mass of central body
 m = mass of orbiting object
 r = distance between center of two objects

Bernoulli's Law

$$\left(P_s + \frac{\rho v^2}{2} \right)_1 = \left(P_s + \frac{\rho v^2}{2} \right)_2$$

P_s = static pressure
 v = velocity
 ρ = density

Atmosphere Parameters

$$T = 15.04 - 0.00649h$$

$$p = 101.29 \left[\frac{(T + 273.1)}{288.08} \right]^{5.256}$$

$$\rho = \frac{p}{0.2869(T + 273.1)}$$

T = temperature
 h = height
 p = pressure
 ρ = density